



TR1: C++ on the *Move*

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Welcome to GDC

- ⌘ Do a little of everything
- ⌘ Expand your horizons
- ⌘ Talk with other developers
- ⌘ Enjoy the city



C++ TR Defined

- ⌕ Technical Report
- ⌕ An “informative document”
- ⌕ Not part of the C++ Standard
- ⌕ May become part of a future standard
- ⌕ Or not



TR1: A History

- ⌚ Formal work began in 2001
- ⌚ Most proposals came from Boost members
- ⌚ Approved in 2006 by ISO
- ⌚ In Spring 2006 all TR1 except math functions added to draft of next Standard
- ⌚ Next Standard (C++0x) is due before the decade is out



What's in TR1

- ⌘ Fixed-sized arrays
- ⌘ Hash tables
- ⌘ Smart pointers
- ⌘ Function objects
- ⌘ Type traits
- ⌘ Random number generators
- ⌘ Tuples
- ⌘ Call wrappers
- ⌘ Regular expressions
- ⌘ Advanced math functions



Why You Should Care

- ③ Efficiency

- ③ TR1 is

 - Lean and mean: more on that in a bit

 - Standard: learn once, use everywhere

 - Proven: avoid the not-invented-here syndrome

 - Available: today, on platforms you care about



Where To Find TR1

④ Boost.org



④ Dinkumware.com



④ Gcc.gnu.org



④ Metrowerks





Getting Started

```
// TR1 header
```

```
#include <array>
```

```
// fully qualified namespace
```

```
std::tr1::array< int, 4 > a;
```

```
// or more likely ...
```

```
using namespace std::tr1;
```

```
array< int, 4 > a;
```



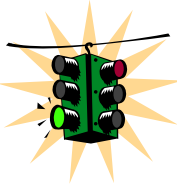

Arrays: True Containers at Last

- ④ `array< class T, size_t N >`
- ④ Size fixed at compile time; contiguous space
- ④ Same performance as C-style arrays
- ④ Member functions you'd expect
begin, end, size, op [], at, front, back
- ④ Works with all std algorithms
- ④ Can be initialized using standard array
initializers

```
std::tr1::array< int,4 > a = { 1,2,3,4 };
```

Arrays: Take Control

⊕ Advantages



Performance

Size is part of the type

Easy to convert array code to/from `std::vector`

More secure: must call `data()` to get ptr

⊖ Disadvantages



Not growable

No `push_back`, `reserve`, `resize`

Must call `data()` to get ptr: inconvenient

`array.swap()` is $O(n)$

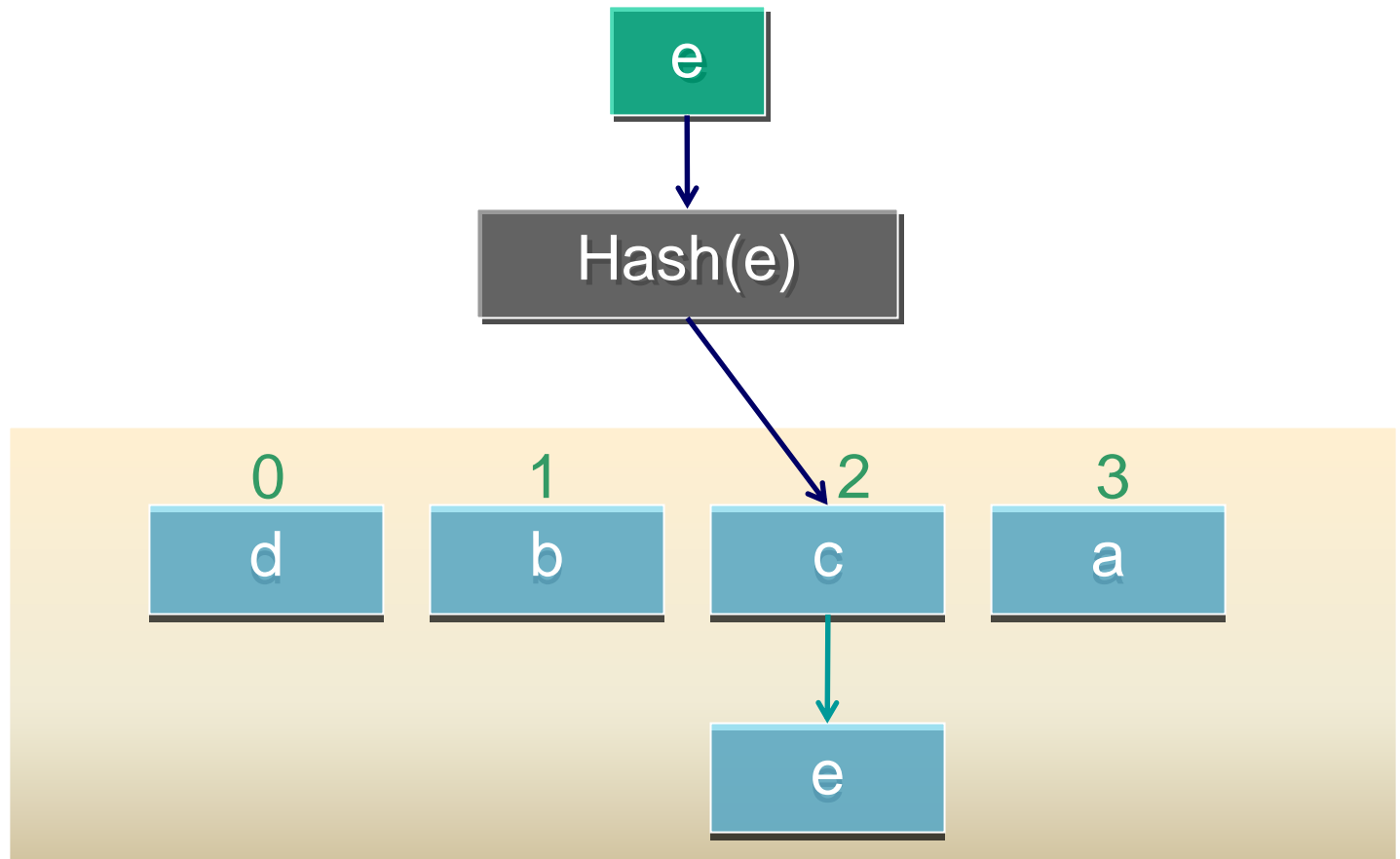
⊕ `vector` is $O(1)$



Hash Tables

- ⌚ Considered for original standard
- ⌚ Basic concept
 - Super-fast search
 - You control the hash algorithm
 - Similar interface to other STL containers
 - Low overhead: on par with set/map

Hash Table Conceptual Diagram





Unordered Associative Containers

- ④ Unordered

A traversal is not ordered like set/map

- ④ Associative

Dictionary pairs (K,T)

- ④ Containers

Work with std iterators and algorithms

- ④ TR1 naming

`std::tr1::unordered_ [multi] set< K >`

`std::tr1::unordered_ [multi] map< K,T >`



Hash Table Code Example

```
#include <unordered_set>
using namespace std::tr1;
unordered_set<int> ht;

ht.insert( 41 ); // add elements
ht.insert( 11 );
ht.insert( 18 );

unordered_set<int>::iterator it;
it = ht.find( 41 ); // find element
```



Real-World Performance

- ⌚ Evaluated three types of objects

Light-weight: int

- ⌚ Hash = `std::tr1::hash<int>`

Medium-weight: `std::complex<double>`

- ⌚ Hash = `(size_t)(real + imag)`

Heavy-weight: bitmap

- ⌚ Allocates, copy ctor calls `memcpy`

- ⌚ Hash = `(size_t)(sum of first few pixels)`

- ⌚ 50,000 items in hash table

- ⌚ Tested on Xbox 360

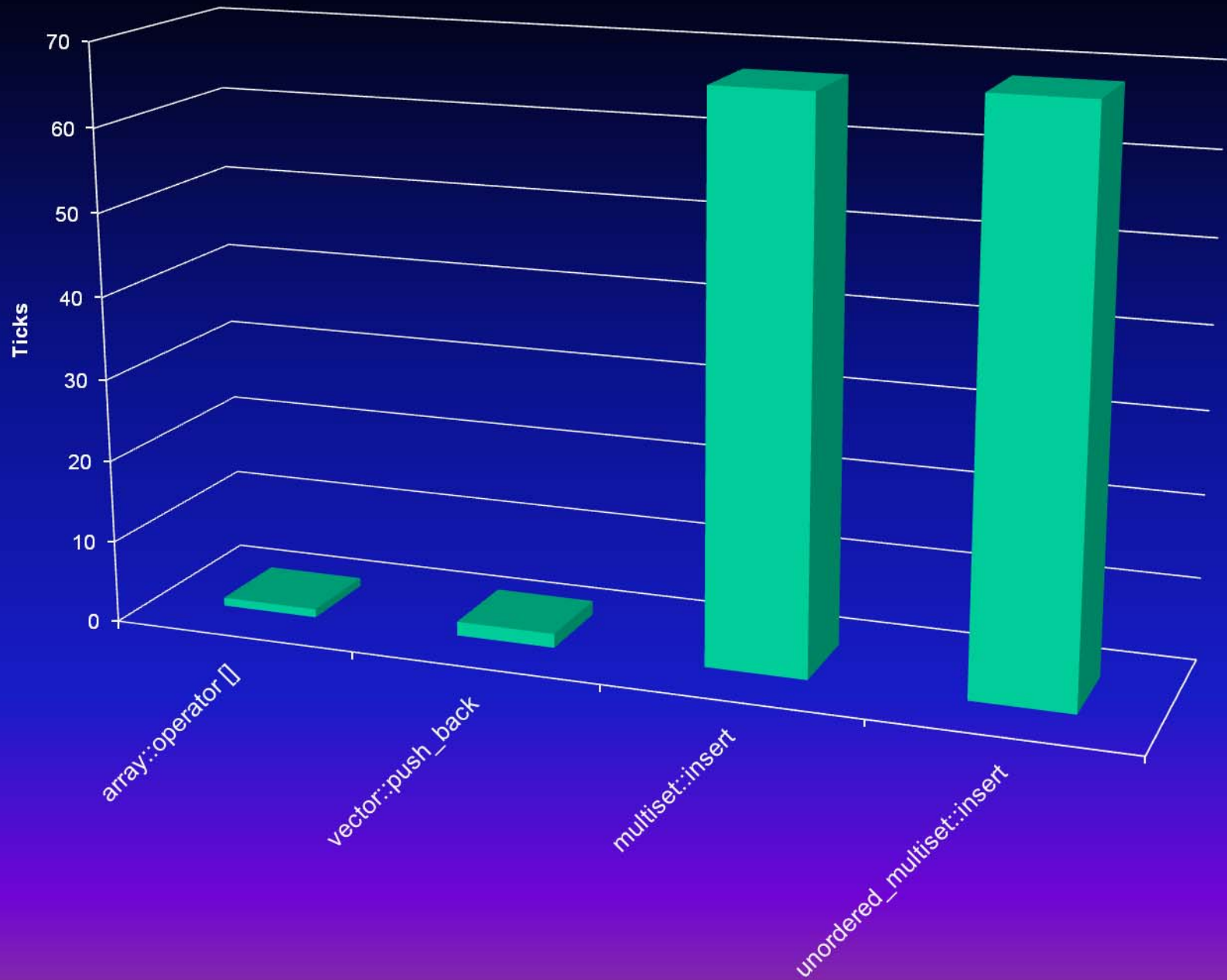
Few perturbations = consistent results



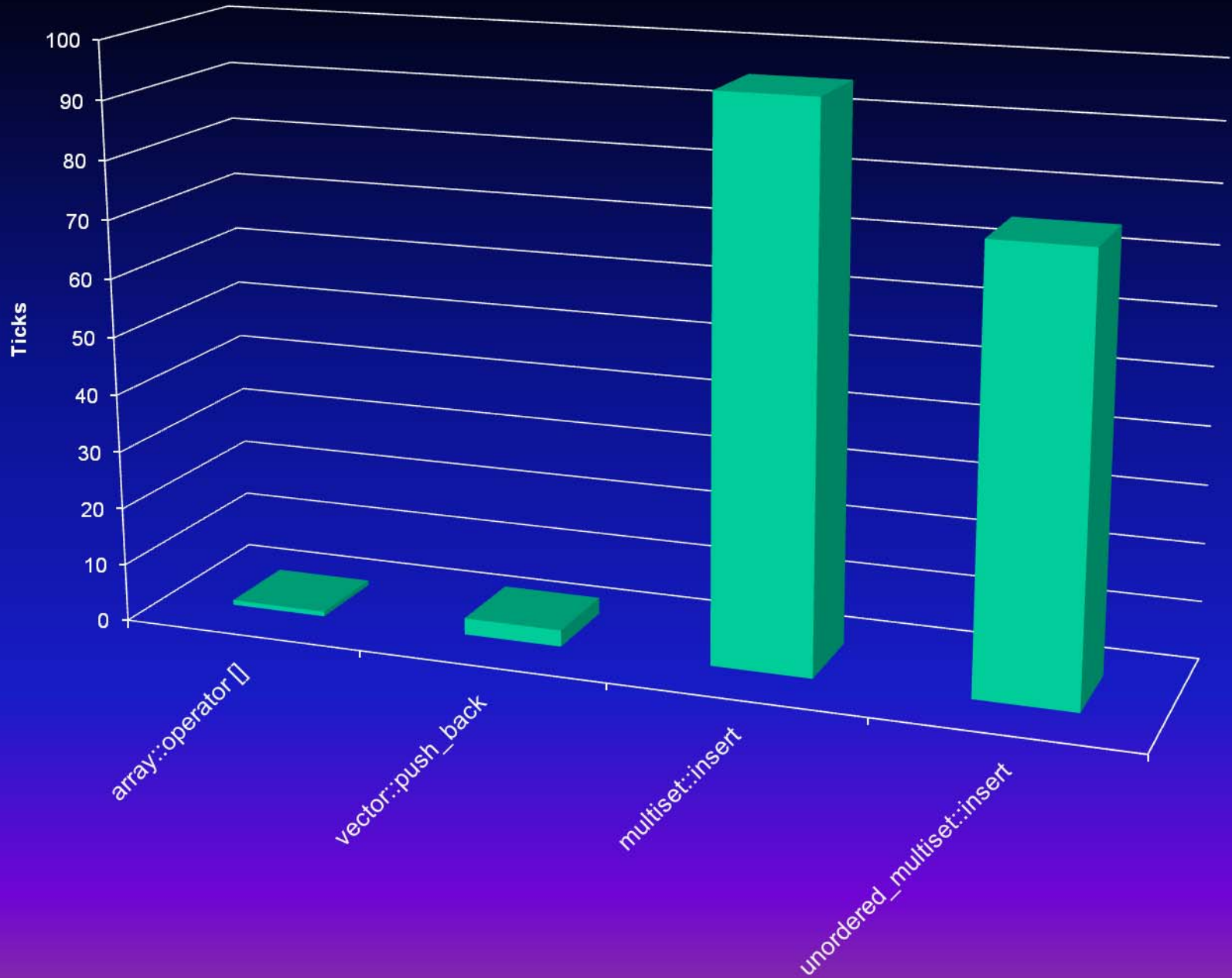
Element Insertion Performance

- ④ Sequence containers (vector, deque)
Complexity: $O(1)$
- ④ Associative containers (set, map)
Complexity: $O(\log n)$
- ④ Unordered associative containers
Average time complexity: $O(1)$
Worst-case time complexity: $O(n)$
- ④ What was real-world performance?

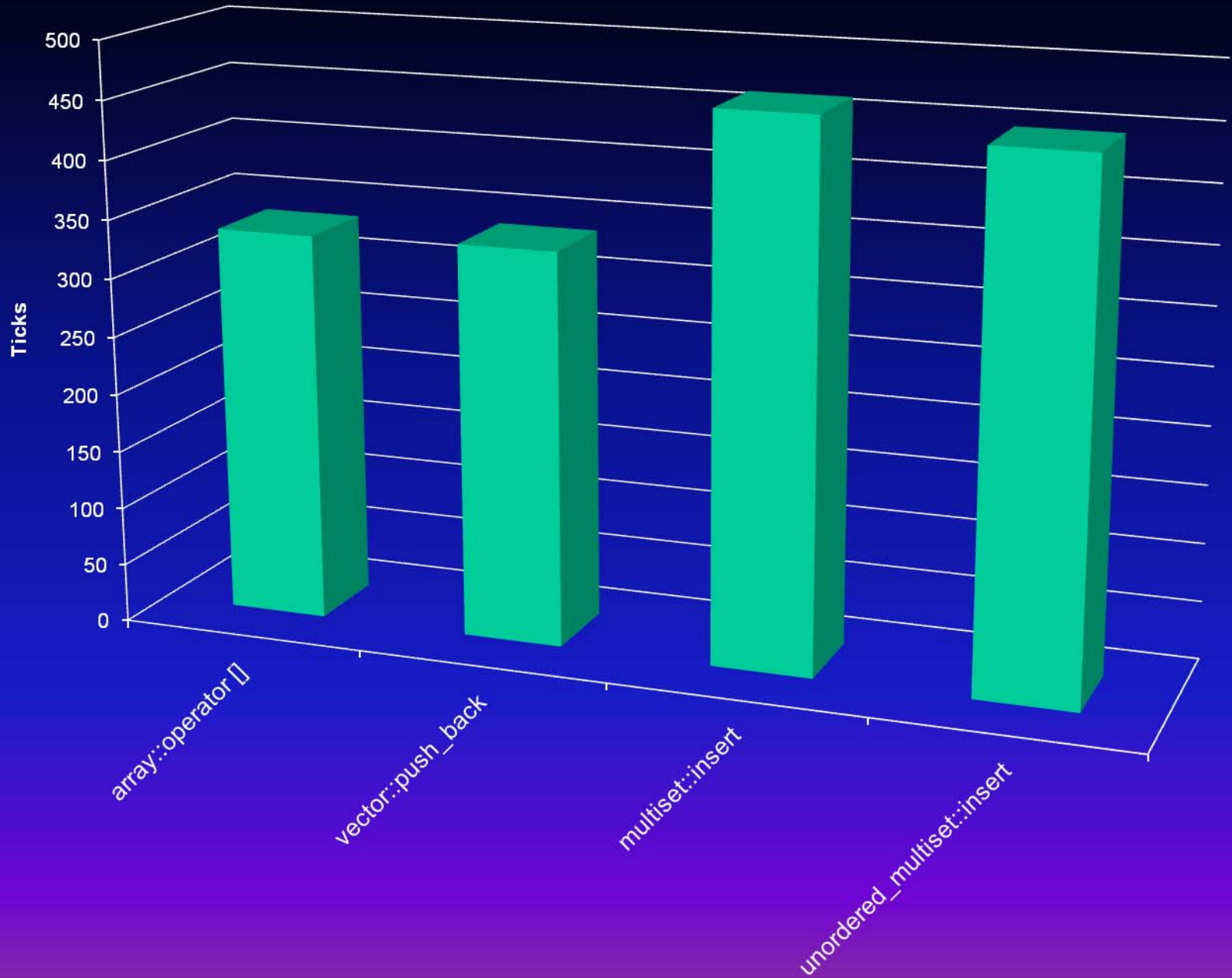
Element Insertion (50,000 int)



Element Insertion (50,000 complex<double>)



Element Insertion (50,000 bitmap)

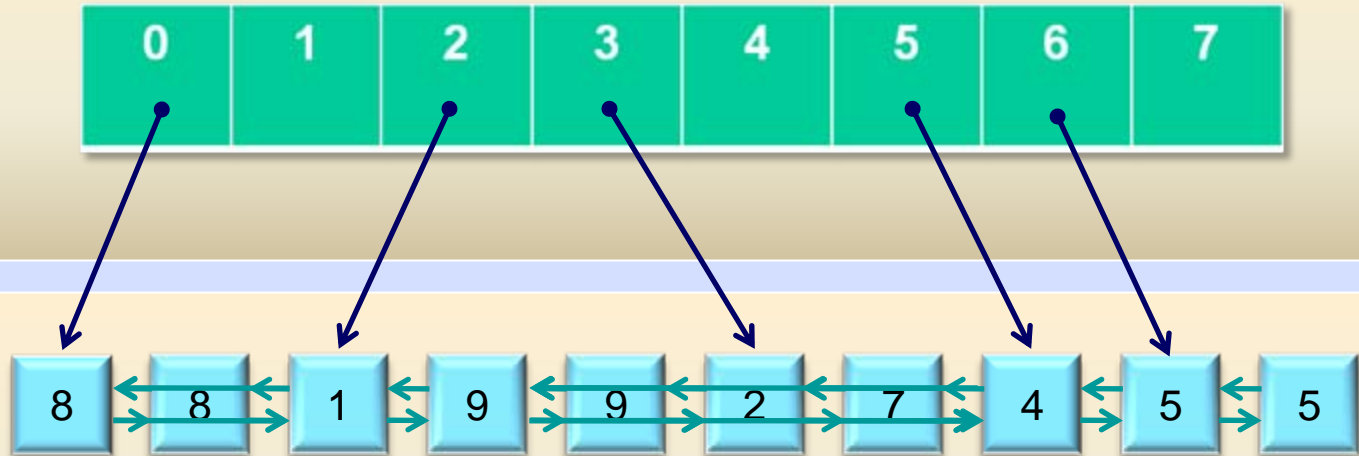


Implementation Example



`unordered_multiset<K>`

`vector<list<K>::iterator> buckets`



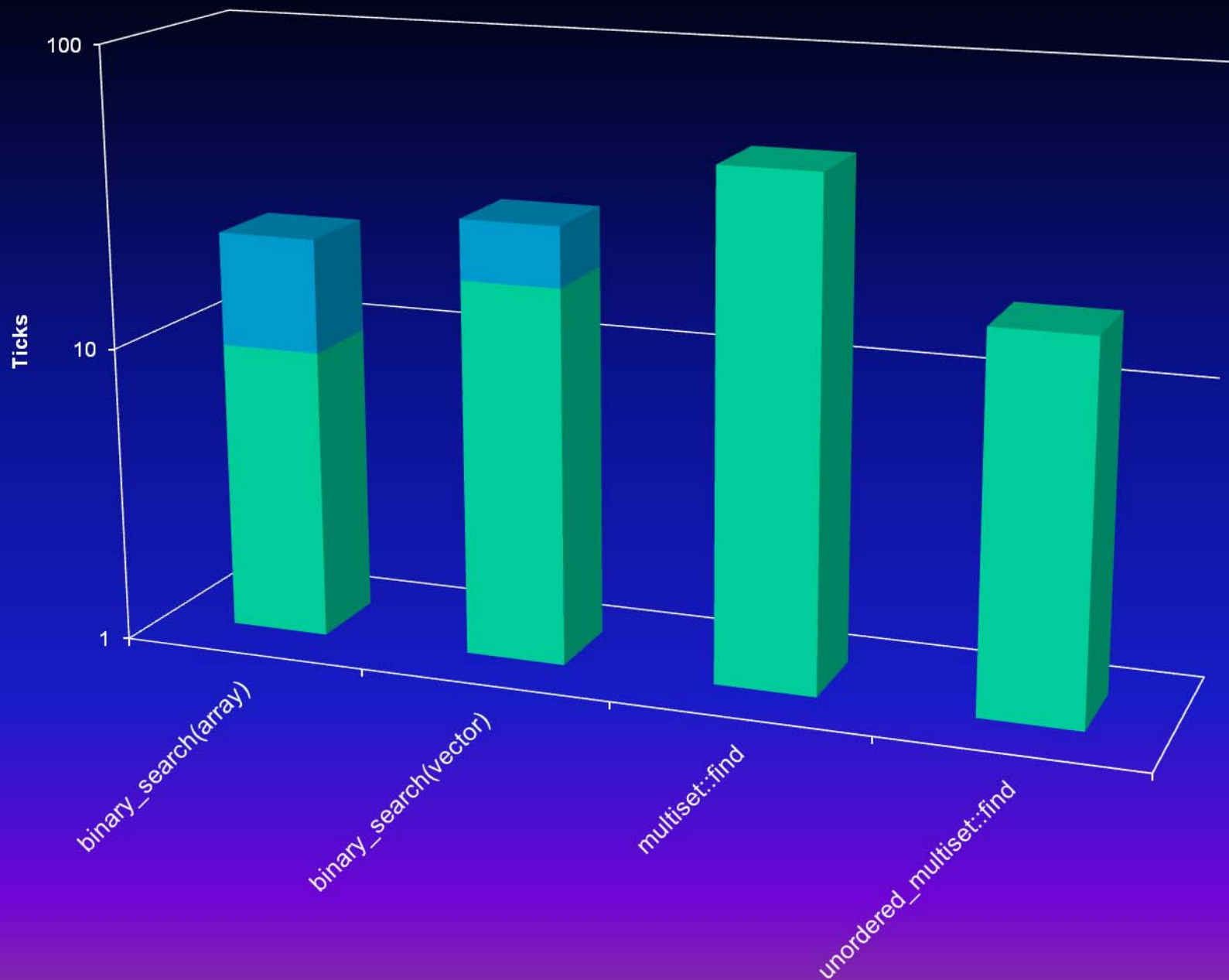
`list<K> elems`



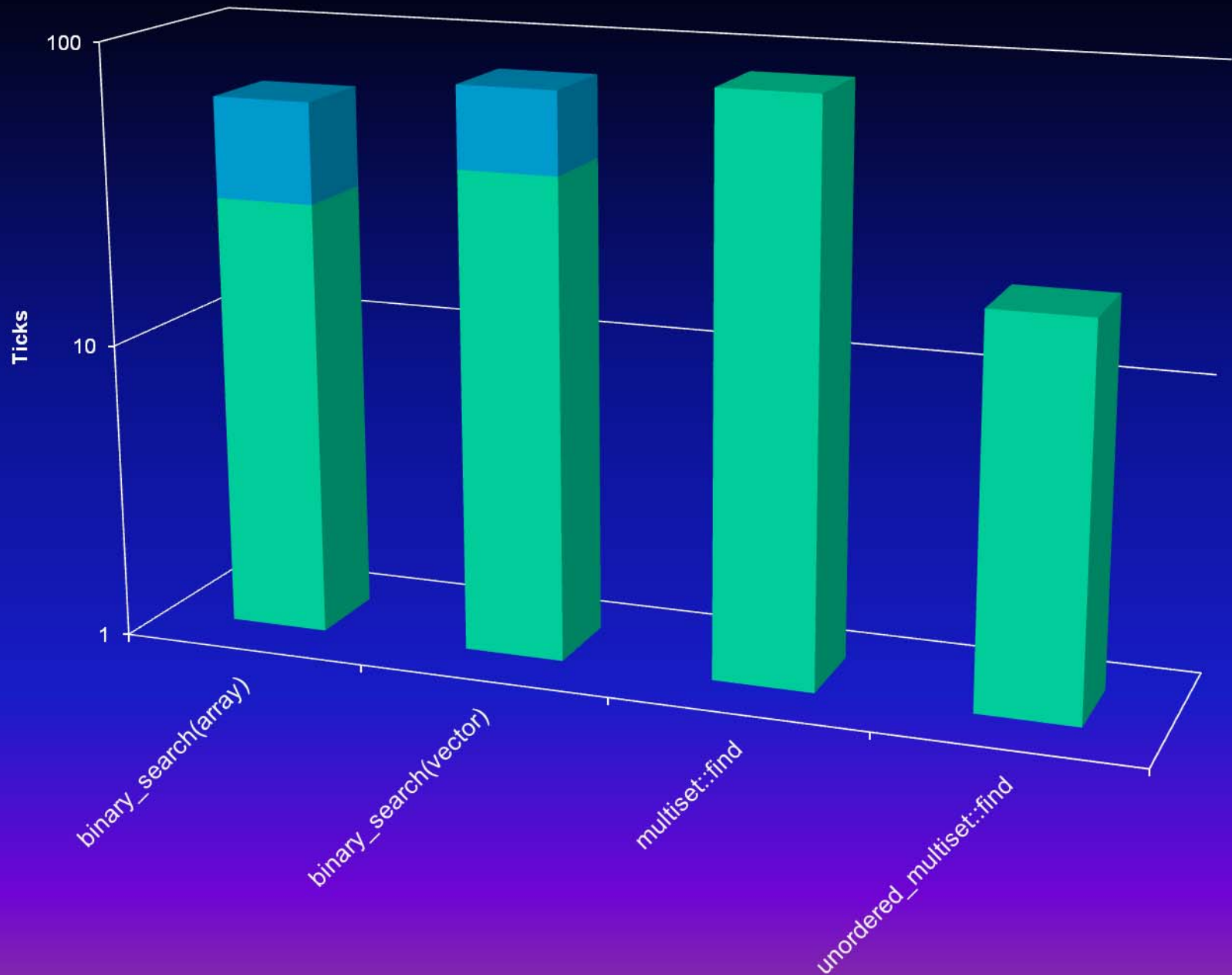
Search Performance

- ④ Sequence containers (vector, array)
Complexity: $O(n)$, $O(\log n)$ if sorted
- ④ Associative containers (set, map)
Complexity: $O(\log n)$
- ④ Unordered associative containers
Average time complexity: $O(1)$
Worst-case time complexity: $O(n)$
- ④ What was real-world performance?

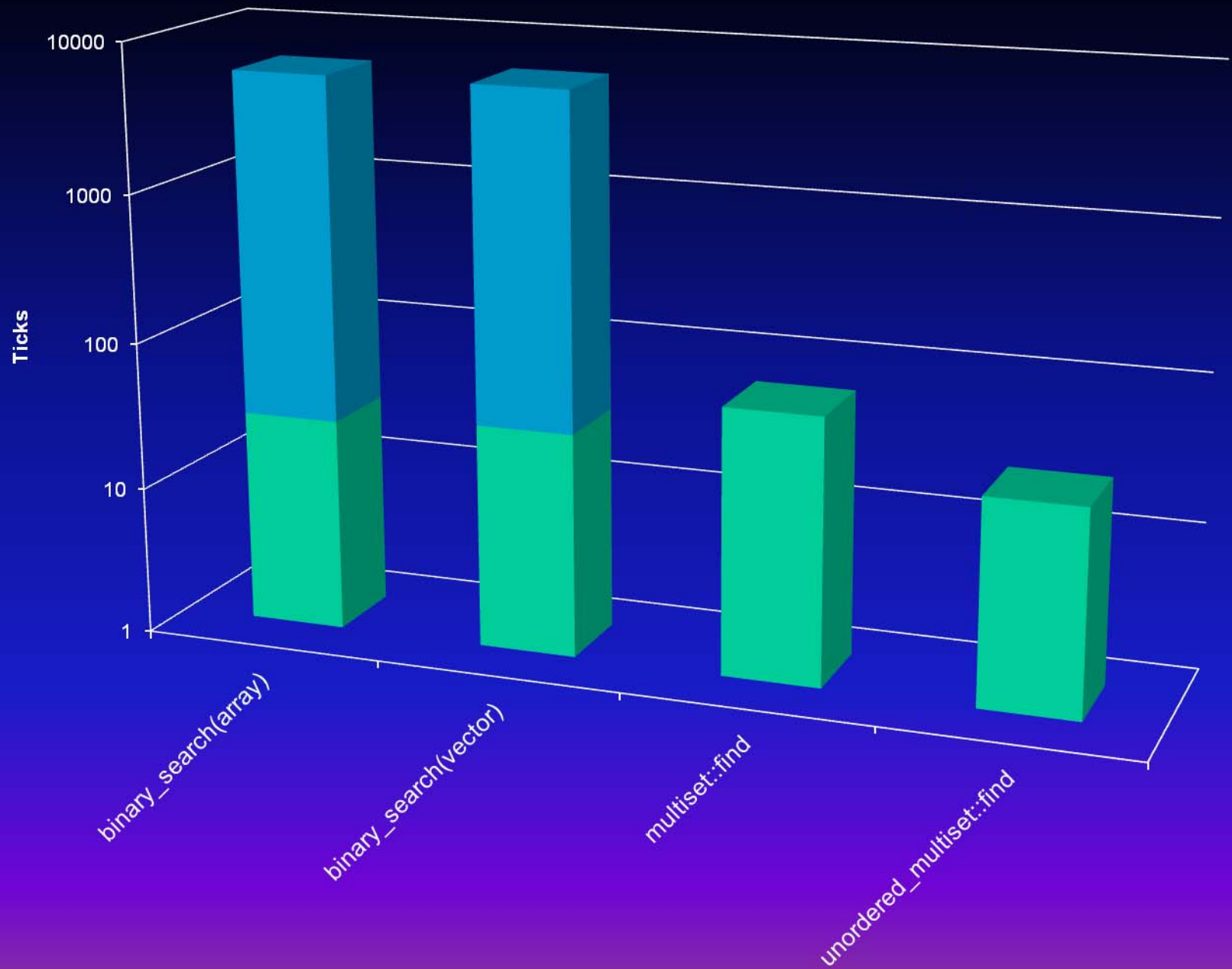
Element Search (50,000 int)



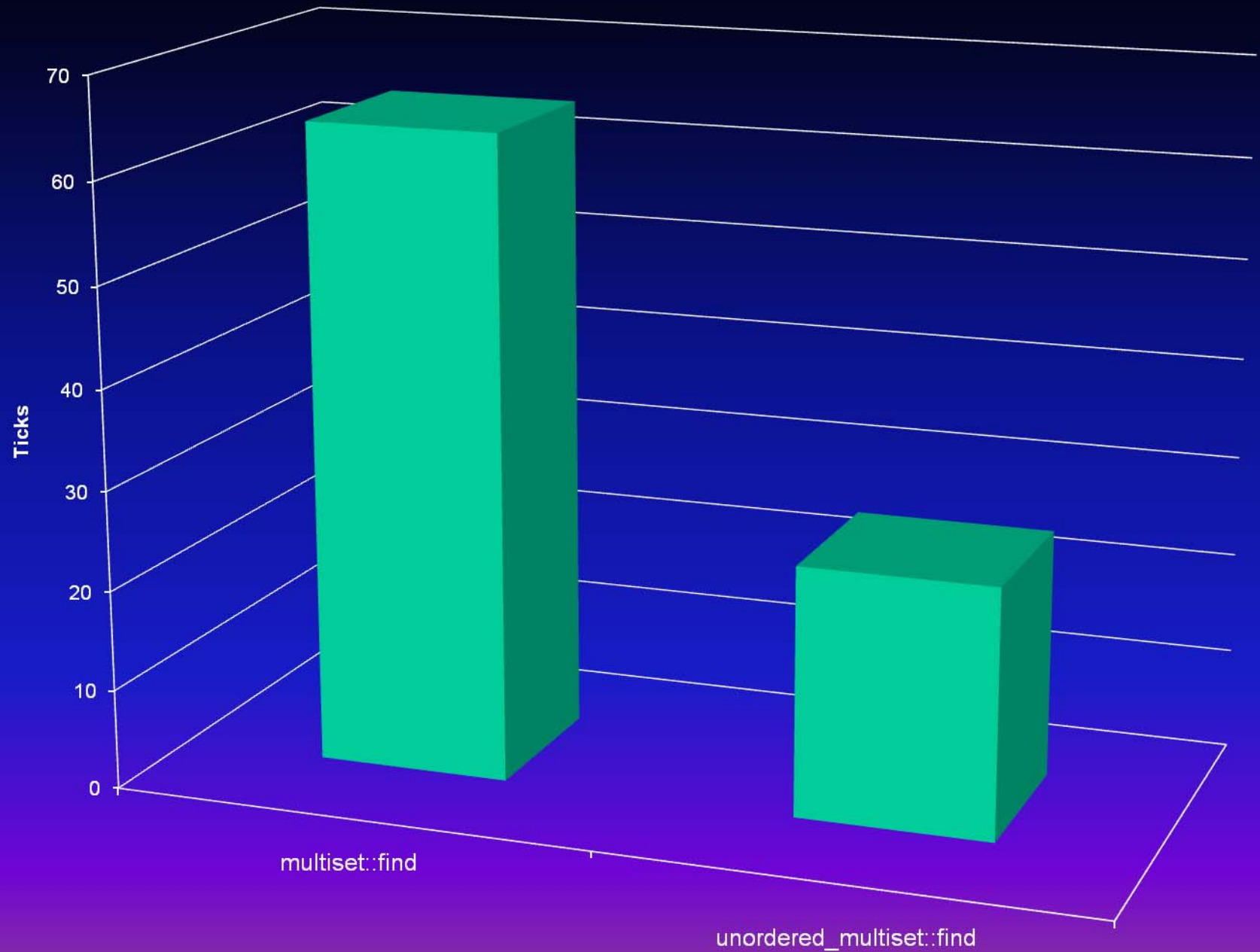
Element Search (50,000 complex<double>)



Element Search (50,000 bitmap)



Container Searching (50,000 bitmap)





Hash Functions

- ⌚ Choosing the right hash function is critical!
- ⌚ Defaults provided for built-ins and `std::string`
- ⌚ For examples, see `<unordered_set>`
- ⌚ Hash references

The Art of Computer Programming, Vol 3, Knuth
Algorithms in C++, Sedgewick



Custom Hash Functions

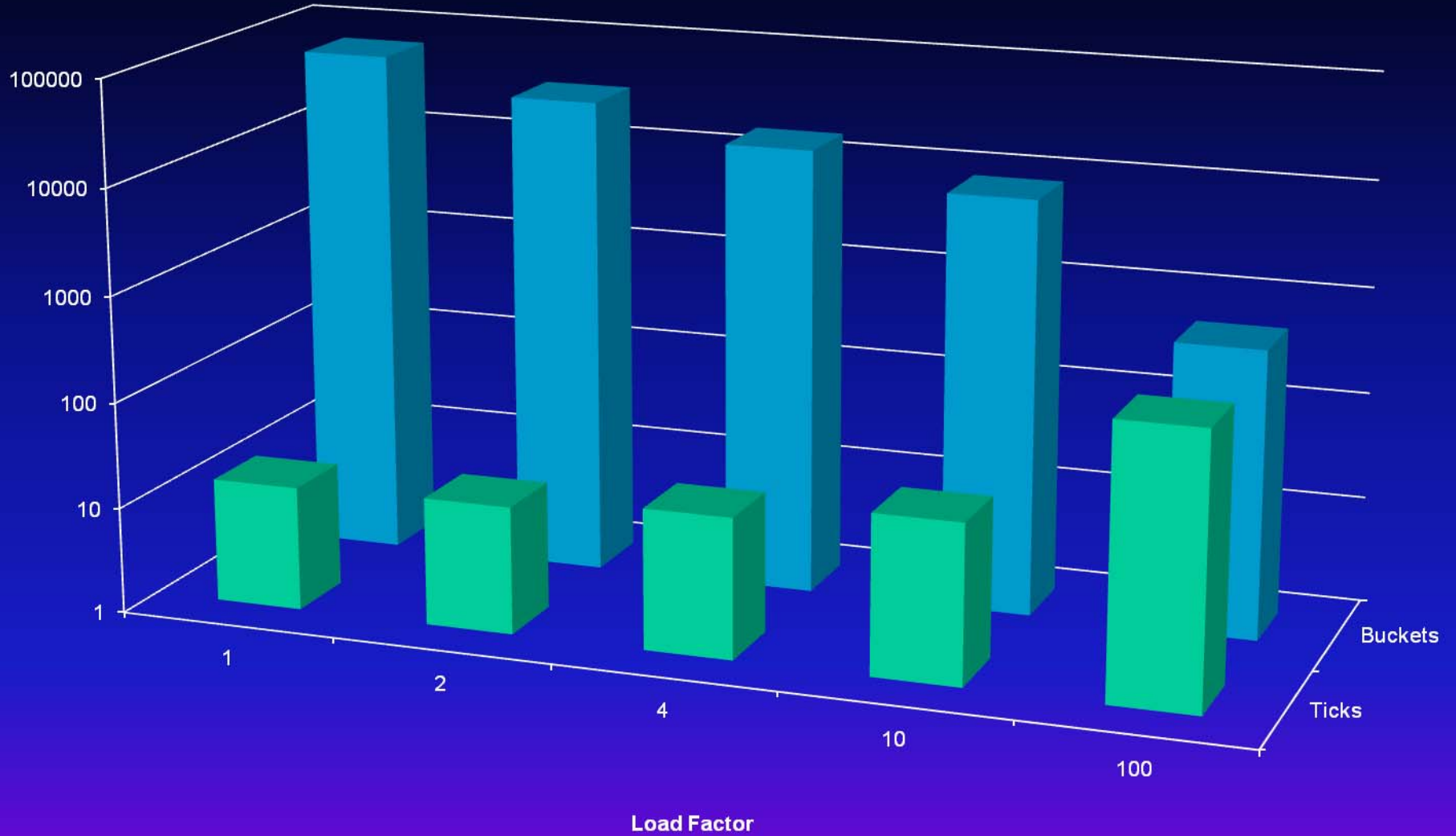
```
typedef std::complex<double> cpx;  
struct CpxHash  
{  
    size_t operator()(const cpx& c) const  
    {  
        return (size_t)(c.real()+c.imag());  
    }  
};  
  
// Specify hash fn as template param  
unordered_set< cpx, CpxHash > ht;
```



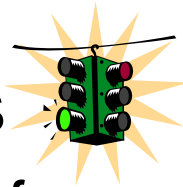

Load Factors and Rehashing

- ⊕ Load factor = `size() / bucket_count()`
- ⊕ Smaller load factor = better performance
- ⊕ You control the maximum load factor
`max_load_factor(float);`
- ⊕ When maximum exceeded, auto rehashes
- ⊕ You can also rehash directly
`rehash(size_type buckets);`

Load Factors and Search Performance



Hash Tables: Take Control

- ⊕ Advantages 
 - Search performance: $O(1)$
 - Tuning options (hash function, load factor)
 - Insertions/deletions amortized $O(1)$
 - Equivalent or smaller overhead/element than set
- ⊕ Disadvantages 
 - Not ordered
 - No `set_union`, `set_intersection`
 - No reverse traversal
 - Depends on great hash function
 - Requires key support `op==()`



Smart Pointers

- ③ C++ resource lifetimes

 - Global

 - Stack-based

 - Static

- ③ No direct support for resources that have an intermediate lifetime

- ③ Enter `shared_ptr<T>`

 - Ensures resources are available as long as needed and disposed when no longer needed



High-Octane Power

- ⌚ Smart ptr copied: ref count incremented
- ⌚ Dtor decrements ref count
- ⌚ Ref count goes to zero: ptr delete'd
- ⌚ Initialize with raw ptr
`shared_ptr<T> sp(new T(...));`
- ⌚ Masquerades as a pointer for common usage
`T t(*sp); // T& operator*() const`
`sp->func(); // T* operator->() const`
- ⌚ Direct access available, too
`p = sp.get(); // T* get() const`



Extended Example, Part A

```
typedef std::tr1::shared_ptr<Bitmap> SPB;  
struct SPBHash  
{  
    size_t operator()(const SPB& bp) const  
    {  
        // hash = raw ptr address  
        return (size_t)( bp.get() );  
    }  
};  
// Store smart bitmaps for fast lookup  
unordered_set< SPB, SPBHash > ht;
```



Extended Example, Part B

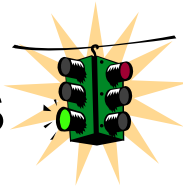
```
// Store bitmaps in hash table
SPB spb( new Bitmap( ... ) );
ht.insert( spb );
ht.insert( ... ); // Insert some more
// Fast lookup
unordered_set<SPB>::iterator it;
it = ht.find( spb );
int w = (*it)->GetWidth();
// Best part: no more code required
// No more resource leaks
```




Smart Pointer Performance

- ③ Object management
 - Ctor: allocates block for ref count info
 - Copy: ref count update
 - Dtor: ref count update; deallocation calls
- ③ Mgmt costs are insignificant for most objects
 - Smart ptrs generally wrap much more costly objs
- ③ Smart ptr access is *equivalent* to raw ptrs
 - *sp produces same code as *p
 - sp-> produces same code as p->

Smart Ptrs: Take Control

- ⊕ Advantages 
 - Automatic resource management
 - Avoid memory leaks
 - Can be stored in containers
 - Tested

- ⊕ Disadvantages 
 - Ref count management overhead
 - Ref count memory overhead
 - Cycles require use of `weak_ptr`
 - May not be thread-safe; chk your implementation



TR1: Take it for a Spin!



Resources

☺ Contact me

Email: pkisensee@msn.com

Homepage: www.tantalon.com/pete.htm

Blog: pkisensee.spaces.live.com

☺ Useful websites

www.boost.org

www.dinkumware.com

gcc.gnu.org

☺ Books and magazines

C++ Standard Library Extensions, Pete Becker

Dr. Dobbs Journal; search on "TR1"